Webinar for the New York City Department of Transportation

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February 17th 2015

Outline

- Motivation
- Method
- Preliminary Results
- Conclusion

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Introduction

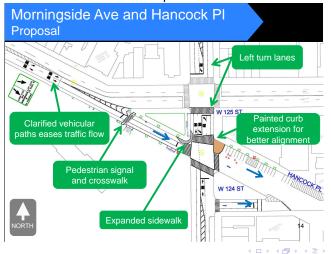
- There is a need for proactive methods of road safety analysis, that do not require to wait for accidents to happen
- In traditional road safety analysis, accidents are never observed: surrogate safety analysis relies on direct observations of traffic and thus provides an understanding of the factors contributing to safety and of collision processes
- Video analysis provides large amounts of traffic data and allows automated, quantitative and objective safety analysis



Case study in New York City at Morningside Ave and Hancock PI



- Case study in New York City at Morningside Ave and Hancock PI
 - collection of data before implementation of counter-measures



- Case study in New York City at Morningside Ave and Hancock PI
 - collection of data before implementation of counter-measures
- Feasibility demonstration of our method



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Collect video data



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- Prepare the analysis: projection from image space to ground space ("map"), annotate zones of interest

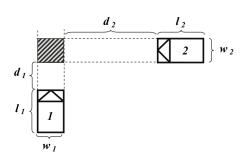
- Collect video data
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- 3 Video analysis: detect, track and classify road users

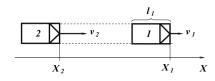


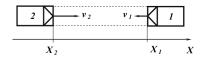
- Collect video data
- Prepare the analysis: projection from image space to ground space ("map"), annotate zones of interest
- Video analysis: detect, track and classify road users
- Identify interactions between pairs of road users (vehicle-pedestrian), compute (safety) indicators (speed, time to collision (TTC), post-encroachment time (PET), etc.)



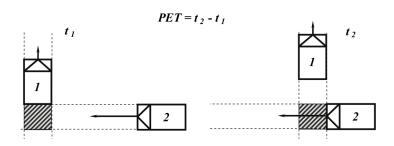
Time to Collision (TTC)







Post-Encroachment Time (PET) and Predicted PET (pPET)



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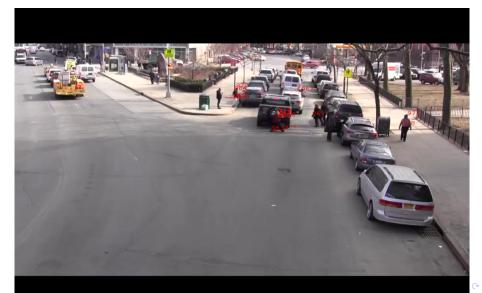
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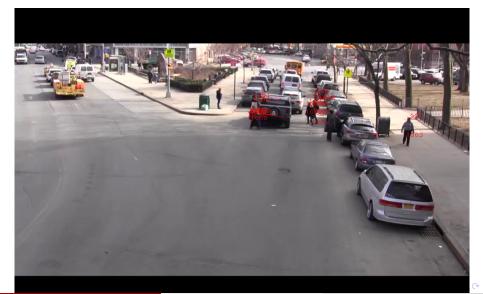


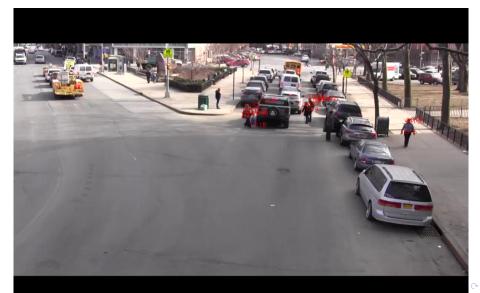


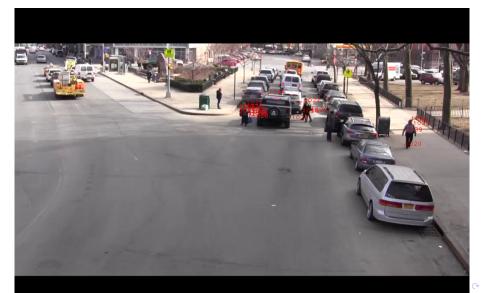


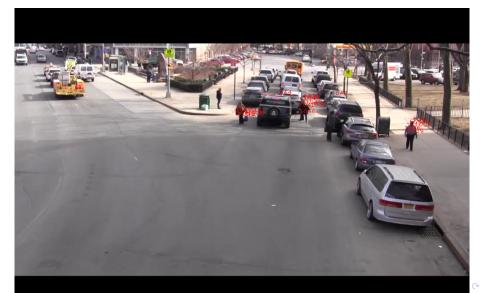














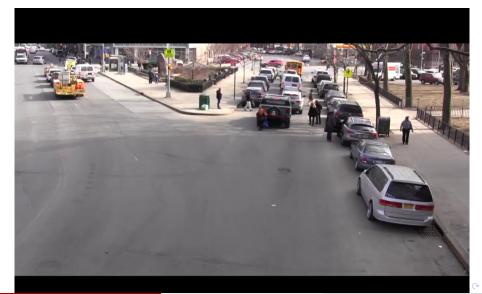


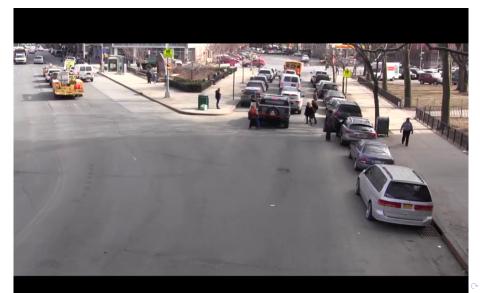






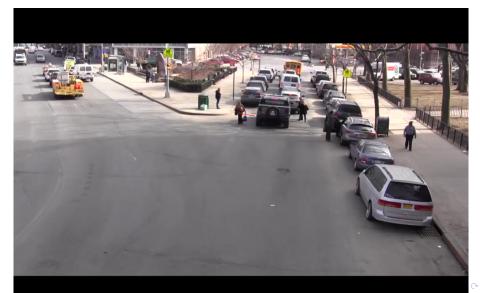












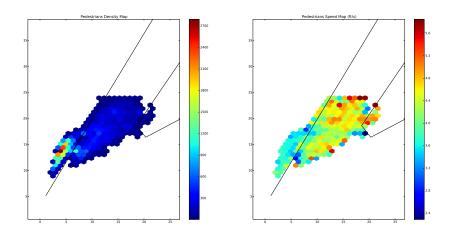
Pedestrian Tracking Issues: Road Users



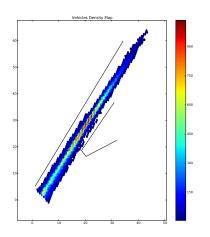
Pedestrian and Vehicle Trajectories

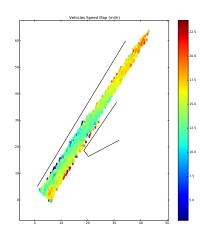


Pedestrian Density and Speed Maps



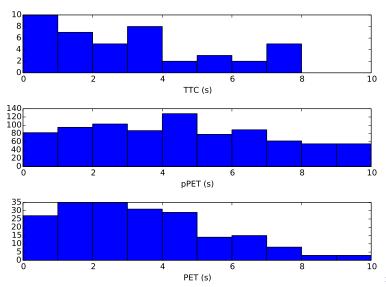
Vehicle Density and Speed Maps



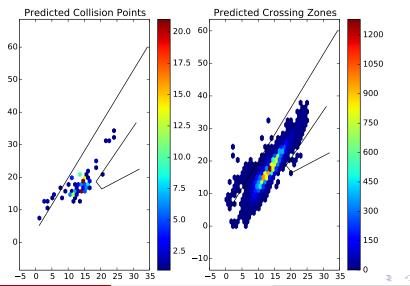




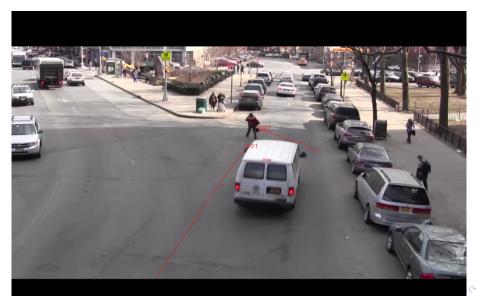
Distributions of Safety Indicators



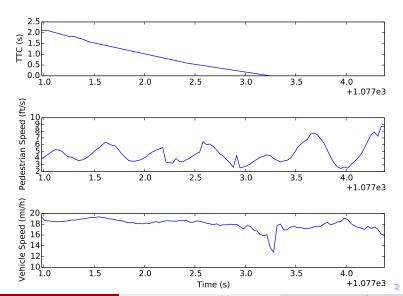
Predicted Collision Points and Crossing Zones



Interesting Interactions



Interesting Interactions: PET = 0 s and $TTC_{min} = 0$ s



Interesting Interactions

Videos: interactions with cars and bikes



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- Even when quality is lacking, the tools may be used for assisted investigation of interactions
- Road user classification is crucial in mixed traffic

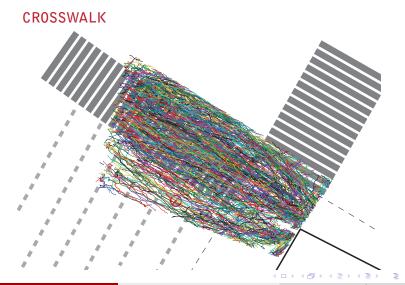


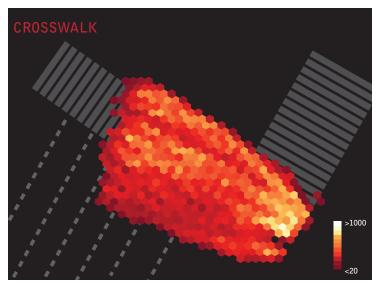


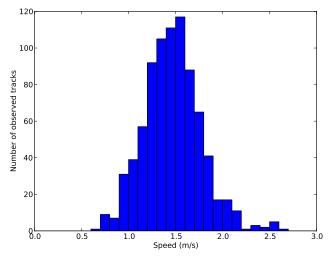














- This work can be easily reproduced: the program for this analysis is available
- Traffic Intelligence open source project https: //bitbucket.org/Nicolas/trafficintelligence





Acknowledgement: Work on Tracking Optimization on Penn Station Video with D. Ettehadhieh & B. Farooq

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Questions?

